



# VEER SURENDRA SAI UNIVERSITY OF TECHNOLOGY

## LESSON PLAN

<b>Semester &gt;&gt;2<sup>nd</sup></b>		<b>Year &gt;&gt; 2015</b>	<b>Contact Hours per week &gt;&gt;4</b>
<b>ENGINEERING MECHANICS</b>		<b>Branch &gt;&gt;</b>	
		<b>Metallurgical &amp; Materials Engineering</b>	
		<b>Total Credit &gt;&gt;4</b>	
		<b>DAY</b>	
		<b>Monday, Thursday, Friday, Saturday</b>	
<b>TEACHER</b>		<b>Mrs Sunita Singh Naik</b>	
<b>Period</b>		<b>Jan 2015-April 2015</b>	
<b>Recommended books &gt;&gt;</b>		<p><b>Text book:</b></p> <ol style="list-style-type: none"> <li>1. Engineering mechanics: S Timoshenko &amp; Young; 4<sup>th</sup> Edition (international edition) MC Graw Hill.</li> </ol> <p><b>Reference books:</b></p> <ol style="list-style-type: none"> <li>1. Fundamental of Engineering mechanics (2<sup>nd</sup> Edition): S Rajesekharan &amp; G ShankaraSubramanium; Vikas Pub. House Pvt Ltd.</li> <li>2. Engineering mechanics: K.L. Kumar; Tata MC Graw Hill.</li> </ol>	
<b>Sl. No.</b>	<b>Lecture No.</b>	<b>Topics to be covered</b>	
<b>MODULE -I</b>			
1	Lecture-01	Introduction of Engineering Mechanics, Types of forces	
2	Lecture-02	System of forces: Concurrent & Coplanar forces	
3	Lecture-03	Composition of forces: Parallelogram law, Triangle law & Polygon law	
4	Lecture-04	Resolution of forces, law of transmissibility, law of Superposition, Free Body Diagram	
5	Lecture-05	Equilibrium of concurrent coplanar forces, Lami's theorem	
6	Lecture-06	Method of projection	
7	Lecture-07	Problem solving	
8	Lecture-08	Method of moment, basic theory and numericals	
9	Lecture-09	Friction: Types, Basic theory	
10	Lecture-10	Related numericals of friction	
11	Lecture-11	Parallel forces on a plane, General case of parallel forces	
12	Lecture-12	Center of parallel forces and center of gravity: Pappus theorem	
13	Lecture-13	Centroid of composite plane figure and curves & related problems	

<b>MODULE -II</b>		
14	Lecture-14	Composition and equilibrium of forces in a plane
15	Lecture-15	Plane trusses:Basic theory
16	Lecture-16	Problems using Method of joints
17	Lecture-17	Problems using Method of sections
18	Lecture-18	Principle of virtual work: Basic theory
19	Lecture-19	Numericals related to Virtual work
20	Lecture-20	Moment of inertia: Plane figure with respect to an axis in its plane and perpendicular to the plane
21	Lecture-21	Perpendicular axis theorem & related problems
22	Lecture-22	Parallel axis theorem & related problems
23	Lecture-23	Doubt clearing class
<b>MODULE-III</b>		
24	Lecture-24	Rectilinear Translation: Kinematics, Principle of dynamics
25	Lecture-25	D'Alembert's Principle Basic theory and numericals
26	Lecture-26	Impulse and Momentum: Basic theory and numericals
27	Lecture 27	Work and energy, Conservation of Energy, Basic theory and problems
28	Lecture 28	Impact: types, coefficient of restitution
29	Lecture 29	Basic theory and numericals related to impact
<b>MODULE-IV</b>		
30	Lecture 30	Curvilinear translation: Kinematics, Equation of motion
31	Lecture 31	Moment & Momentum
32	Lecture 32	Projectile motion Basic theory
33	Lecture 33	Numerical related to projectile
34	Lecture-34	D'Alembert's principle of curvilinear motion
35	Lecture-35	Kinematics of rotation of rigid body
36	Lecture-36	Numerical Problem related to rotation of rigid body
37	Lecture-37	<b>Class-Test</b>
38	Lecture -38	<b>Brief Review &amp; discussion Revision &amp; Clarification of Doubts</b>
39	Lecture -39	
40	Lecture -40	

**Signature of Teacher**